# Smart Radar Level Transmitter
# Model: MDRA6

## I.Product Overview

### 1.1 Introduction

MDRA6 radar level meter is an 80GHz high-frequency intelligent level measuring instrument, which outputs (4~20) mA analog signal, with a maximum range of 35 meters. The antenna is further optimized, and the new fast microprocessor can perform signal analysis and processing at a higher rate, so that the instrument can be used for level measurement of liquid tank, solid silo and other general working conditions.

### 1.2 Principle

The radar level meter transmits a continuous radar wave signal from the antenna. This signal is FM continuous wave, or FMCW for short. There is a frequency difference between the continuous wave transmitted from the radar level meter antenna and the echo returned from the object surface. The frequency difference is proportional to the distance between the antenna and the object surface. After receiving the echo, the electronic components use special processing such as Fast Fourier Transform (FFT), and use a unique high-precision algorithm, The instrument can accurately measure the level height.



A. Low adjustment
B. Measuring range
C. High level adjustment
D. Distance
E. Blind area
H. Material height
R. Measuring reference point
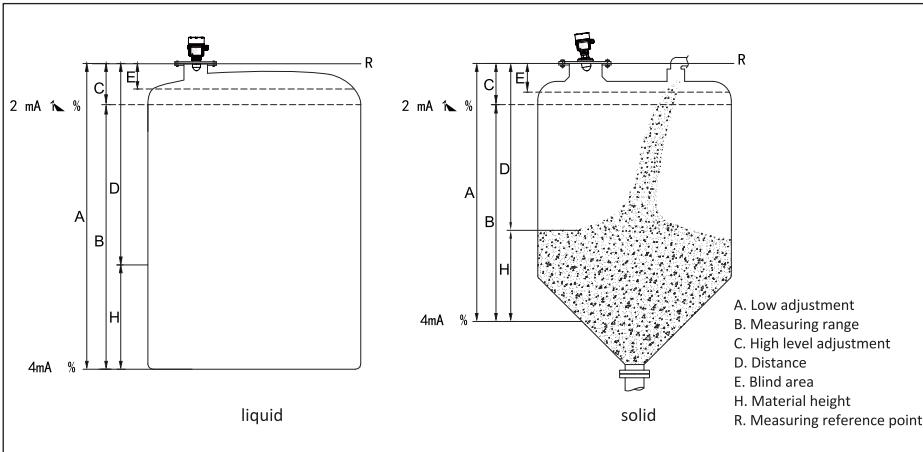
figure 1

### 1.3 Features

▶ The radar level meter adopts the working frequency of 80GHz and has the following characteristics:

▶ Non contact measurement, no wear, no pollution;

▶ Small antenna size, easy to install;

▶ Shorter wavelength, better reflection on inclined solid surface;

▶ The measurement blind area is smaller, and good results will be achieved for small tanks;

▶ The beam angle is small and the energy is concentrated, which not only enhances the echo ability, but also helps to avoid interference;

▶ It is almost not affected by the changes of water vapor, temperature and pressure in the atmosphere;

▶ 80GHz frequency is the best choice for measuring solid and low dielectric constant medium, which is satisfied with the dielectric constant of the measured medium

## 2.Product Introduction

| | Features: solid/liquid can be measured, with angle measurement function, simple installation,high precision, strong anti-interference ability and small beam angle. |
|---|---|
| MDRA6 | Application: applicable to general working conditions, such as liquid level height measurement in water industry, level height measurement of small range solid silo. |
| | Measuring range: 10m/20mm/35m |
| | Precision: ± 2mm |
| | Process connection: G1 ½ "A |
| | Process temperature: - 40~80 ℃ |
| | Process pressure: - 0.1~0.3Mpa |
| | Frequency range: 80GHz |
| | Signal output: 4~20mA/24V DC two-wire system |
| | 4~20mA/24V DC/HART two-wire system |
| | Bluetooth function: optional |
| | Explosion proof grade: Exia IIC T6 Ga |
| | Protection grade: IP67 |

## 3.Installation

Please pay attention to the following items to ensure that the instrument can be installed correctly.
1. Please reserve enough space for installation.
2. Please avoid installation occasions with strong vibration.

### 3.1 Installation position
▶The instrument shall be installed at 1/6 or 1/4 of the tank diameter.
▶ If the tank diameter is small, the minimum installation distance is ≥ 200mm.



figure 2

Note:
① Datum plane
② Center of container or axis of symmetry
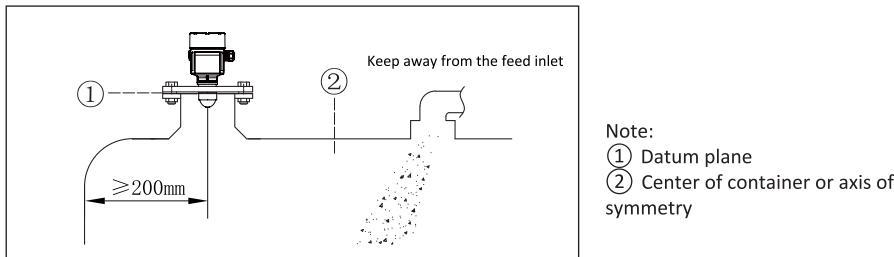
▶ The conical flat roof tank is installed in the middle of the tank top and can be measured to the bottom of the conical tank.
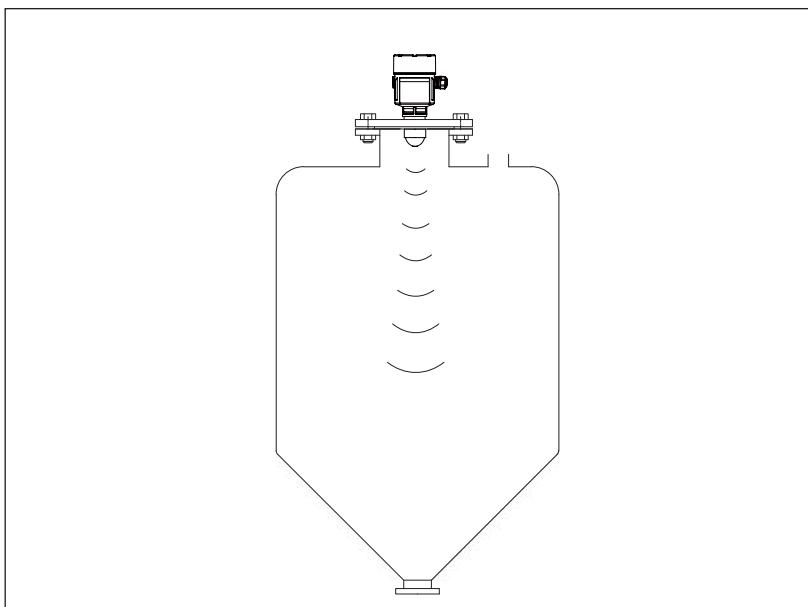


figure 3

▶ For the storage tank with material pile, the antenna shall be vertically aligned with the slope. If the slope is uneven and the pile angle is large, universal flange must be used to adjust the angle of the conical antenna so that the conical antenna can be aligned with the slope as much as possible.
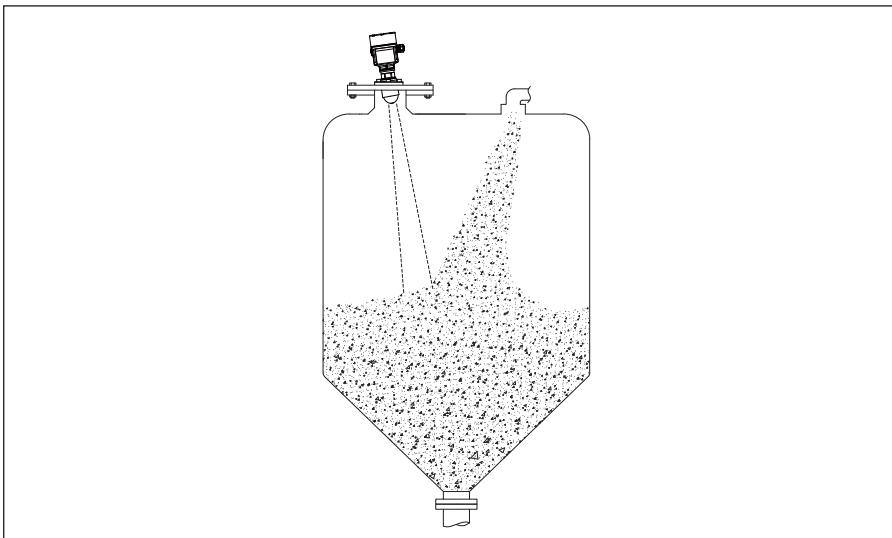


figure 4

▶ Bracket installation

| D | d | L |
|---|---|---|
| 83 | 61 | 143.5 |



M8 nut

L1

Radar bracket
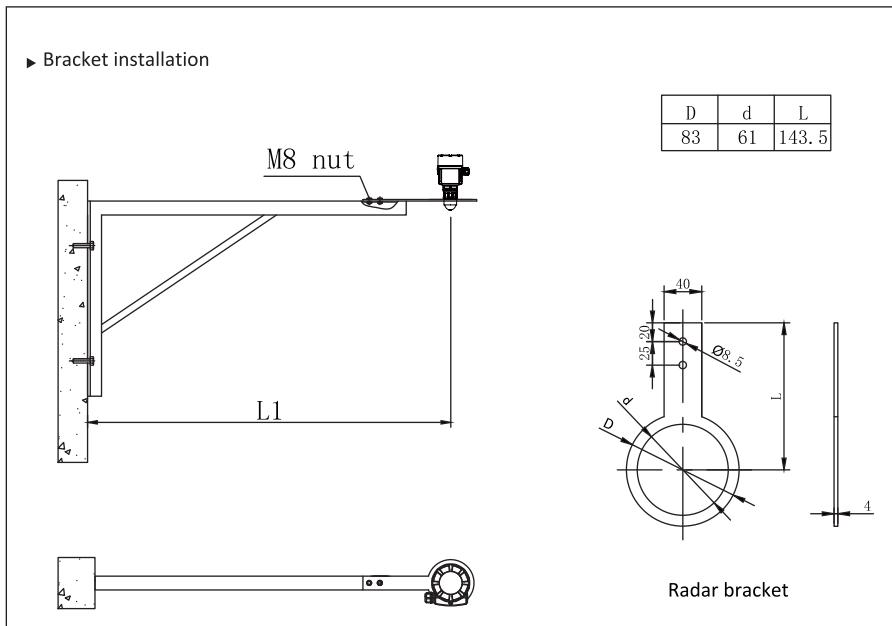
figure 5

### 3.2 Typical wrong installation

▶ **It cannot be installed above the feed inlet.**



① correct

② wrong
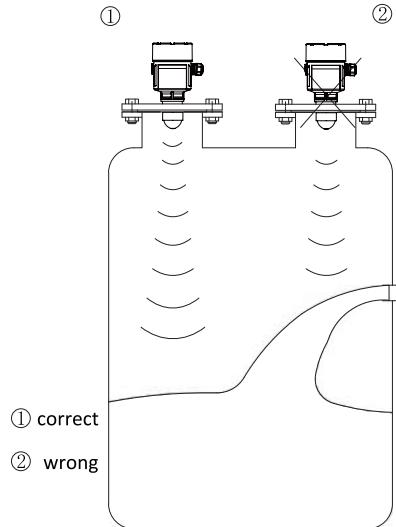
figure 6

▶ The instrument cannot be installed in the middle of the arc tank top, which will be affected by multiple echoes. Since the arc tank roof can concentrate multiple echoes, and the multiple echoes may be stronger than the real echo signal, it cannot be installed in the center.



① correct

② wrong
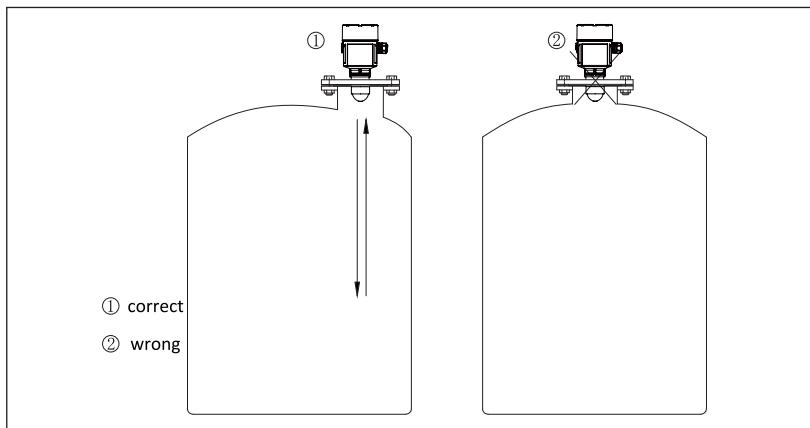
figure 7

### 3.3 Tank nozzle

▶ It is strongly recommended that the length of vessel installation nozzle on site should be ≤ 200mm, and it is a very reasonable installation method that the length of vessel installation nozzle should be ≤ 200mm.

▶ If the length of the vessel connecting pipe is long, please refer to Figure 8. The longest installed connecting pipe shall be as small as possible as the size shown in Figure 8, and the end must be ground smooth without burrs and other protrusions. If necessary, use the "false echo storage" function to eliminate the reflected signal at the end of the container nozzle, which can also achieve better measurement results.

| Nozzle diameter d | | Nozzle length h |
|---|---|---|
| 50mm | 2 | ≤200mm |
| 80mm | 3 | ≤300mm |
| 100mm | 4 | ≤400mm |
| 150mm | 5 | ≤500mm |
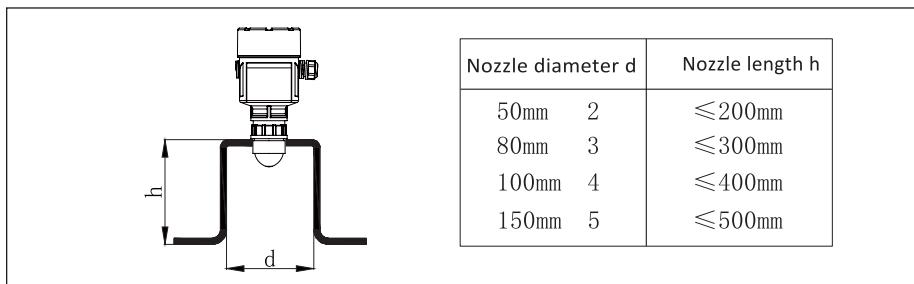
figure 8

### 3.4 Launch  angle and false reflection

The transmitting angle of the radar level meter depends on the antenna size.
If the transmitted radar signal can reach the surface of the medium vertically and there is no device in the container to block and reflect the signal, this measurement condition is the best.

0m
10m
0.52m 0m 0.52m

0m
20m
1.05m 0m 1.05m

0m
35m
1.83m 0m 1.83m
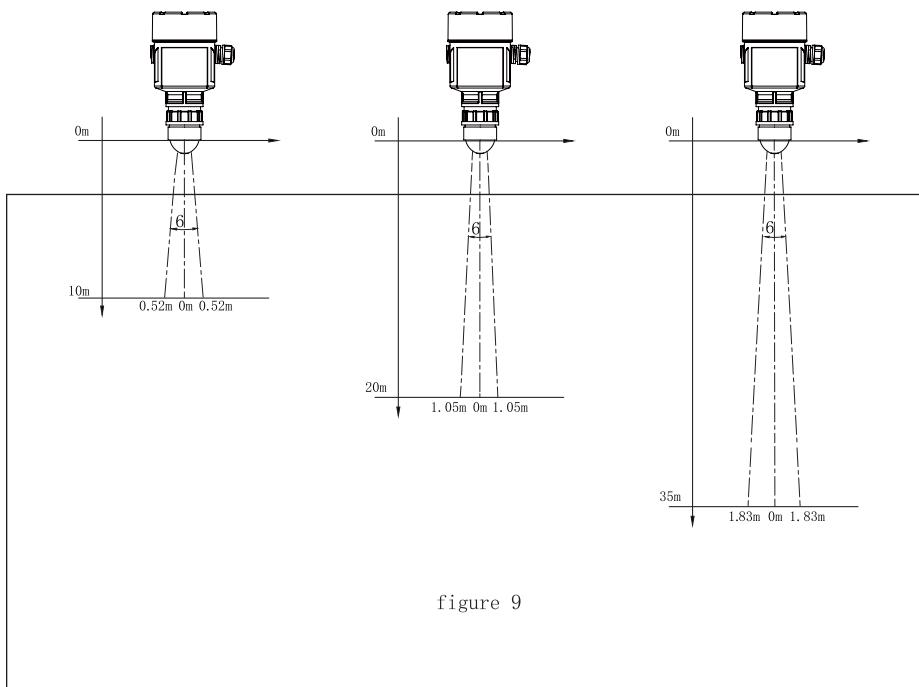
figure 9

## 4.Electrical Connection

4.1 Supply voltage

(4~20) mA/HART (two-wire system) power supply 24V DC

The power supply and output current signal share a two core shielded cable. For intrinsically safe type, a safety barrier must be added between the power supply and the instrument.

4.2 Installation of connecting cable

Cable outer diameter: 6~9mm (M20 × 1.5)          3.5mm~8.7mm( ½ NPT)

Shielded cables are generally used for wiring.

(4~20) mA/HART (two-wire system) power supply cable can use two core cable

4.3 Cable shielding and wiring

Ideally, the shield wire should be grounded at both ends. However, it should be noted that there will be grounding compensation current. When both ends are grounded, a capacitor with grounding potential can be connected at the grounding end (such as in the switch cabinet). (For example: 1 μ F； 1500V）. The grounding with the lowest resistance shall be adopted. (Note: If the instrument is used in explosion-proof area, due to potential output, both ends must not be grounded)

**4.4 Wiring mode**

(1) 24VDC power supply, 4-20mA output



Two wire wiring diagram

24V DC
4~20mA
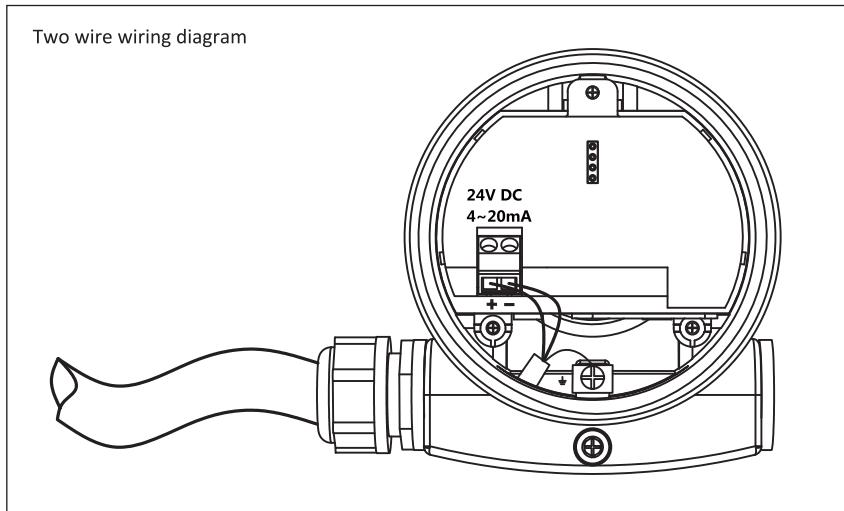
figure 10

**Explosion proof connection**:

The explosion-proof type of this product is intrinsically safe. Explosion proof sign: Exia Ⅱ C T6 Ga. This product is applicable to the continuous level measurement of combustible media below the explosion proof level of Exia Ⅱ C T6 Ga.

This product must be powered by a safety barrier. The safety barrier is the associated equipment of this product, and the explosion-proof type is intrinsically safe. Explosion proof sign: [Exia Ga] IIC, power supply voltage 24V DC, short circuit current 100mA, working current (4~20) mA.

All cables shall be shielded cables, and the maximum length from the instrument to the safety barrier is 500m. Ui=30VDC，Ii=100mA，Pi=0.75W，Ci=0μF，Li=0mH    The radar level meter must be grounded during installation. Other related equipment without explosion-proof inspection shall not be used.

**Intrinsically safe explosion-proof wiring diagram:**



Explosion proof area | Non explosion proof area
Exia IIC T6 Ga

Safety barrier

4~20mA

Intrinsically safe terminal  (4~20)mA  IN    (4~20)mA  OUT   Non intrinsically safe terminal

24V  OUT              24V  IN

either-or

Ui:30V DC
Ii:100mA
Ci:0μF
Li:0mH
Pi:0.75W

**Barrier parameters :** Uo:＋28VDC    Io:100mA  Co、Lo
Um:250VAC/DC    Po:0.7W
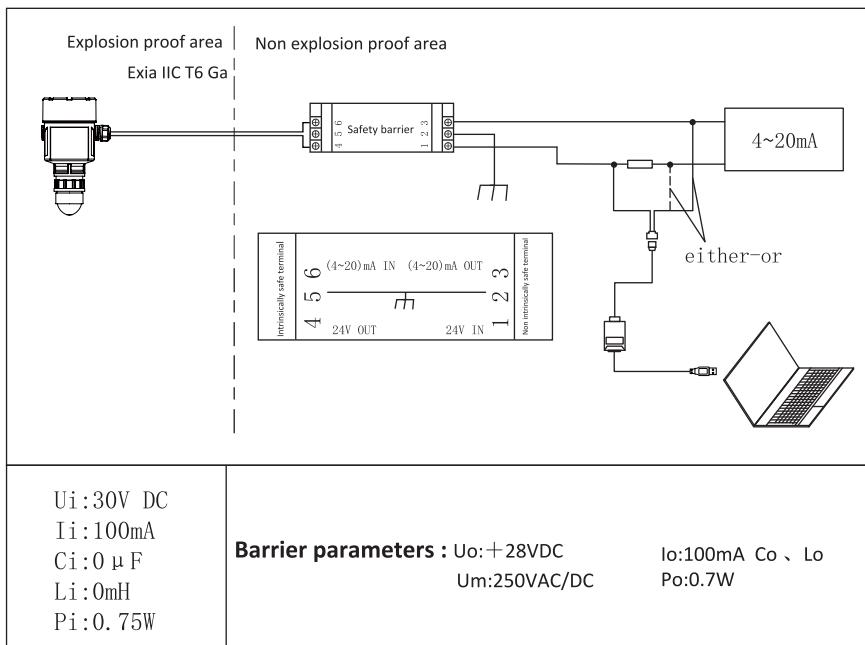
figure 11

The distribution parameters of the connecting cable between the safety barrier and the level meter shall meet the following requirements:

$$Uo \leq Ui \quad Io \leq Ii \quad Po \leq Pi \quad Co \geq Cc+Ci \quad Lo \geq Lc+Li$$

Note:
Uo: maximum output voltage of safety barrier
Co: maximum external capacitance of safety barrier
Cc: Maximum allowable distributed capacitance of connecting cable
Ci: maximum internal capacitance of level meter

Io: maximum output current of safety barrier
Lo: maximum external inductance of safety barrier
Lc: Maximum allowable distributed inductance of connecting cable
Li: Maximum internal inductance of level meter

### 4.5 Safety guidance

All electrical connection work must be carried out under the condition of power failure. Please follow the instructions in the instrument manual!

Please observe the requirements of local electrical installation regulations.

Please observe the local requirements for personnel health and safety regulations. All operations on the electrical components of the instrument must be completed by professionals who have received formal training.

Please check the nameplate of the instrument to ensure that the product specifications provided meets your requirements. Please ensure that the supply voltage is consistent with the requirements on the nameplate of the instrument.

### 4.6 Protection grade

MDRA6 radar level meter fully meets the requirements of protection grade IP67. Please ensure the waterproof of cable sealing head. As shown in the right figure:

How to ensure that the installation meets the requirements of IP67:

Make sure that the sealing head is not damaged

Please ensure that the cable is not damaged. Please ensure that the cable used meets the requirements of the electrical connection specification. Before entering the electrical interface, bend the cable downward to ensure that water will not flow into the shell, see ①

Please tighten the cable sealing head, see ②

Please tighten the unused electrical interface with blind plug, see ③
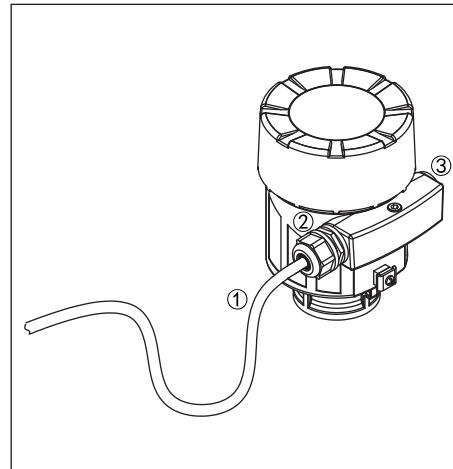
figure 12

## 5. Technical Parameters

General data

| Product model | MDRA6 |
|---|---|
| Process connection | thread G1½"A |
| weight | 700g |
| Process temperature | -40~80℃ |
| Antenna material | ABS/PTFE |
| Shell material | ABS |
| Degree of protection | IP67 |

| Supply voltage | Two-wire system | Standard | 16~26V DC |
|---|---|---|---|
| | | Intrinsically safe | 21.6~26.4V DC |
| | | power waste | Max.0.54W |
| | | Allowable ripple | −<100Hz　　　　Uss<1V<br>−(100~100k)Hz　Uss<10mV |
| Cable parameters | | Cable entry | 1 *M20 × 1.5 Cable inlet (cable diameter 6~9mm)<br>1 *blind plug M20×1.5 |
| Output parameters | | output signal | 4~20mA/HART |
| | | resolving power | 1.6μA |
| | | Fault output | 20.5mA, 22mA, 3.9mA |
| | | Damping time | 0~100s Adjustable |
| Housing | | Enclosure seal | Fluorine glue |
| | | Upper cover window | PC |

**characteristic parameter**

| Product model | MDRA6 |
|---|---|
| range | 10m/20m/35m |
| accuracy | $\pm 2$mm |
| blind area | 0.05m |
| General parameters | Microwave frequency 77~81GHz<br>communication interface HART communication protocol<br>Measurement interval About 1 second (depending on parameter settings)<br>Adjust time About 1 second (depending on parameter settings)<br>Vibration resistance Mechanical vibration 10m/s$^2$, (10~150) Hz<br>Non repeatability ≤ 1mm (already included in the measurement deviation)<br>Display resolution 1mm<br>relative humidity ＜95% |

### 6 Commissioning

6.1 Programmer debugging

6.1.1 Key function

Debug the instrument through the 4 keys on the programming module. The language of the debug menu is optional. After debugging, it is generally only used for display, and the measured value can be read out clearly through the glass window.



27.5100 m

16.576mA          H
17.93 C

1 LCD display
2 Key
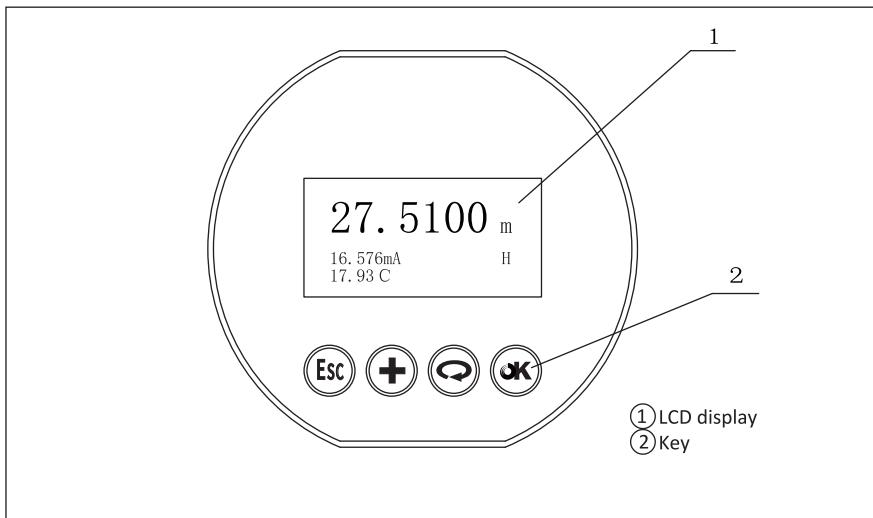
Key functions

| | |
|---|---|
| (ESC) key | -Exit the programming state or go back to the previous menu<br>-Switch between display value and echo curve interface (at home page) |
| (+) key | -Toggle menu items<br>-Change cursor position<br>-Modify parameter value, 0~9 infinite loop<br>-Toggle the curve display mode or home page display mode |
| (⟳) key | –Toggle menu items<br>–Change cursor position |
| (OK) key | -Enter programming state<br>-Confirm programming items<br>-Confirm parameter modification |

sheet 1

**6.1.2 Commissioning steps**
(1) Enter the main menu
In the running state, pressing key **OK** will display the programming main menu. There is a triangle cursor on the left side of the main menu. Press key ⟳ to change the triangle cursor position downward, and press key **+** to change the triangle cursor position upward,Press key **OK** to enter the menu pointed by the cursor, and press key **ESC** to exit the current menu

The display interface is as follows:

▶ Basic settings
Display
Service
Advanced Features
Information

(2) Set range

High low setting

000.000 m
035.000 m

Enter the "Basic Setting" menu, and the programmer will directly display the first submenu "High Low Setting". The display interface is as follows:

For example:

① In general, if the distance from the measuring reference point to the tank bottom is 35m, the "low position" should be set to 35.000m; "High position" 00.000m.

② Under special circumstances, the field production process needs to set the maximum output below the zero point of the instrument.

For example, if the 10m tank process requires that the tank is full when the material is injected 2m below the zero point of the instrument to prevent danger, the "low position" should be set as 10.000m, and the "High position" should be set as 02.000m.

The display interface is as follows:

| high position | 00.000 m |
| Low position | 35.000 m |

| high position | 02.000 m |
| Low position | 10.000 m |

After the high position adjustment setting is completed, continue to cycle the submenu until the item "measuring range" is displayed. Note that this range is not the output range of the instrument, but the maximum range for the instrument to process the reflected echo (set value: range setting ≥ low adjustment).

For example, the process requirement starts from the tank bottom, and the output range is 10m. If the "measuring range" is set to 9m, the "low level" is set to 10m, and the "high level adjustment" is set to 0m. The output range of the instrument has not changed, but the material level of 1m at the bottom of the tank can not participate in the measurement, and the instrument can not find the signal at the bottom of the tank when the tank is empty, which is easy to cause value jump.

(3) Blind zone setting

When there is a fixed obstacle near the surface of the distance sensor that interferes with the measurement, and the maximum material height will not reach the obstacle, it can be used for the blind zone setting function to avoid measurement errors. Press **OK** to enter the blind zone setting and editing interface, select**+** or ⊜ key to set parameters, and press **OK** to confirm.

**Blind zone setting**

| 00.100 | m |

13

**(4) Set display content**
After entering the "Display" menu, the first submenu is "Display Contents". After setting the options, the instrument programmer will display the corresponding contents. The factory default value is generally the material level, that is, the height of the material level displayed on the panel when the programmer has not entered any menu.

The display interface is as follows:

```
 Show contents          show contents
                      ─────────────────
 Material  ▶          ◉ Material height
 height               ○ Empty height
```
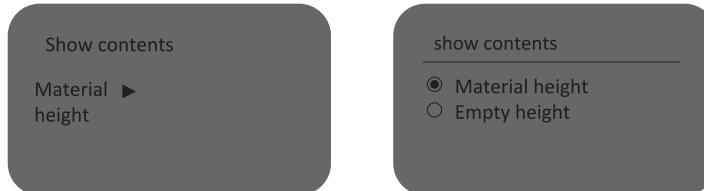
Definition of display content:
①  Space height: measure the distance from the reference point to the medium surface;
②  Material level: material level height, which is equal to "low level" minus "empty height"

**(5) False echo storage function**
The false echo storage function can eliminate the influence of interference wave on the real signal under certain conditions.
Enter the "Service" menu. The first submenu is "False Echo". Click OK to enter the setting interface, where four options are displayed.
The display interface is as follows:

```
 False echo            start   │ 00.000 │m
                       end     │ 00.000 │m
 000.000      m        height  │    008 │dB
 000.000      m
```

**(6) Select current output**
 After the setting of "false echo" is completed, press the key to cycle the menu to display "current output".
The display interface is as follows:

```
 Current output

     4-20 mA      ▶
```
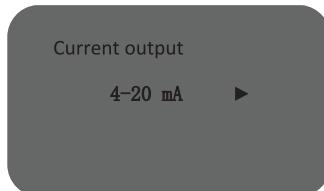
Current output: the current output direction can be selected when the instrument is working. The factory default setting is 4-20mA, and the output current is proportional to the material height; After 20-4mA is selected, the output current is inversely proportional to the material height, that is, the output current is proportional to the space height.

Schedule

```
Basic settings ──────→ High low setting ──────→ Liquid
      │                       │                     │
      ↓                       ↓                     ↓
   display ──────────→ Material property         Solid
      │                       │
      ↓                       ↓
   service            Damping time
      │                       │
      ↓                       ↓
advanced setting ←── Output Mapping ──────→ Storage box / Reservoir
      │                       │
      ↓                       ↓
information          measuring range
                            │
                            ↓
                    Blind zone setting

                    show contents ──────→ Empty height / Material height
                            │
                            ↓
                    LCD contrast
```

Original Accumulation ← advanced setting

Primary filtering

Secondary filtering

Echo index

Nonextreme suppression

Narrow wave filter

Window Settings

sampling

Clutter setting

algorithm

Echo locking

Response rate

Similarity

Effective proportion

signal gain

Head wave distance

First wave proportion

Factory echo learning

date of manufacture / Software version

Sensor type / serial number

False echo ──────→ Start / End / Height

Current output ──────→ 4-20mA / 20-4mA

Unit of measurement ──────→ m / cm / mm

language ──────→ English

Bus Address

Distance bias

Current bias

Current simulation

Current function

Threshold setting ──────→ width / height

password

**6.2 Upper computer software debugging**

6.2.1 Connecting with upper computer through HART

①MDRA6
②USB interface
③HART Adapter
④250 Ω resistance
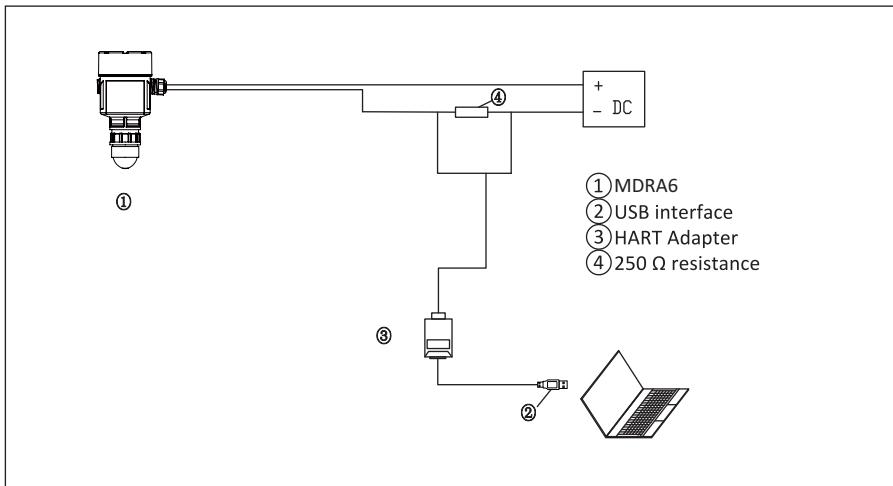
figure 14

**6.2.2 Commissioning of HART handheld programmer**

MDRA6 can be programmed with HART handheld programmer

① MDRA6
② HART handheld programmer
③ 250 Ω resistance
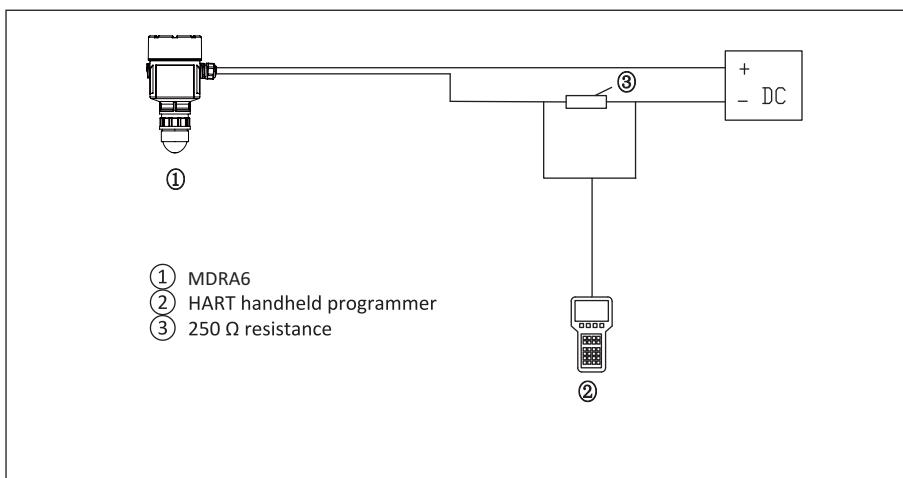
figure15

### 6.2.3 Bluetooth debugging

MDRA6 can be debugged with Bluetooth function



① MDRA6
② Smartphone
③ Tablet
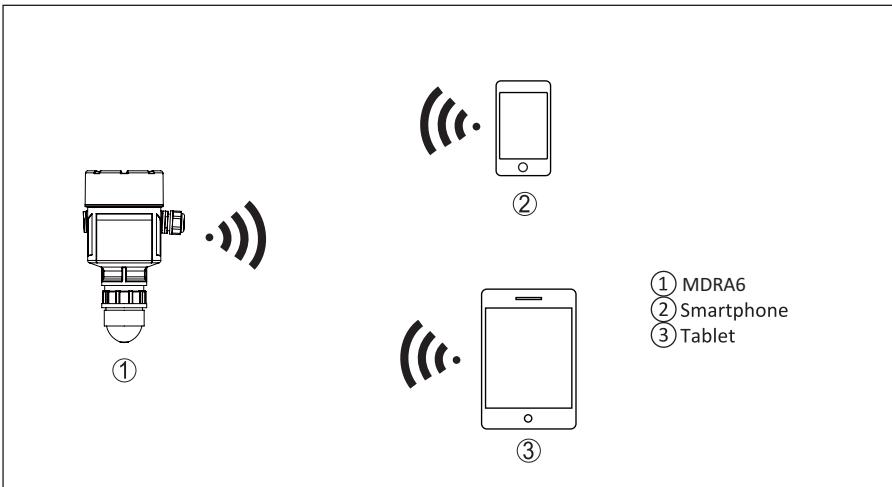
figure 16

### 7. Product Structure Dimensions (Unit: mm)



MDRA6

138

207

G1½″A

## 8 .Linear Graph

| Beam angle | accuracy |
|:---:|:---:|
| 6 | $\pm 2$mm |

5mm
2mm
−2mm
−5mm
0.1m
10m

| Beam angle | accuracy |
|:---:|:---:|
| 6 | $\pm 2$mm |

5mm
2mm
−2mm
−5mm
0.1m
20m

| Beam angle | accuracy |
|:---:|:---:|
| 6 | $\pm 2$mm |

5mm
2mm
−2mm
−5mm
0.1m
35m
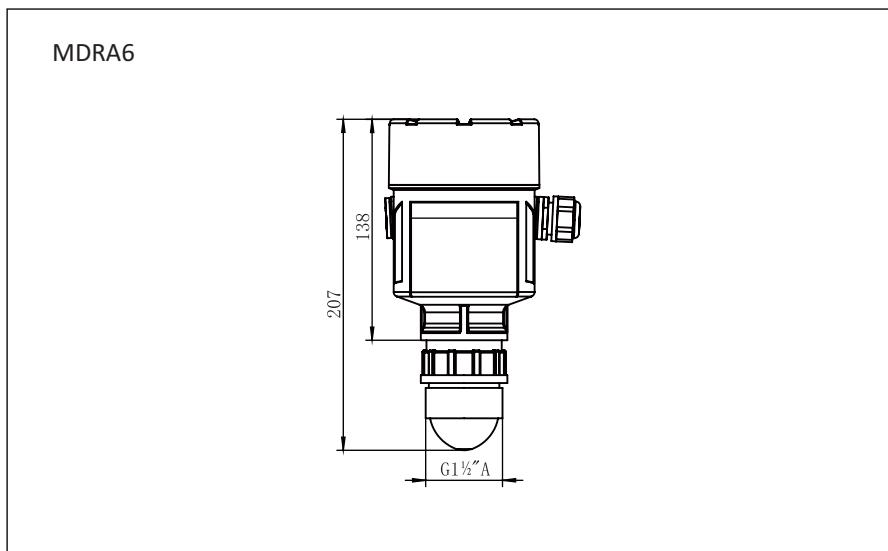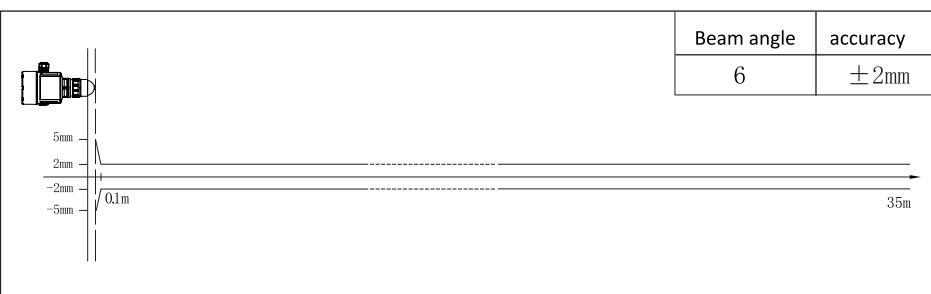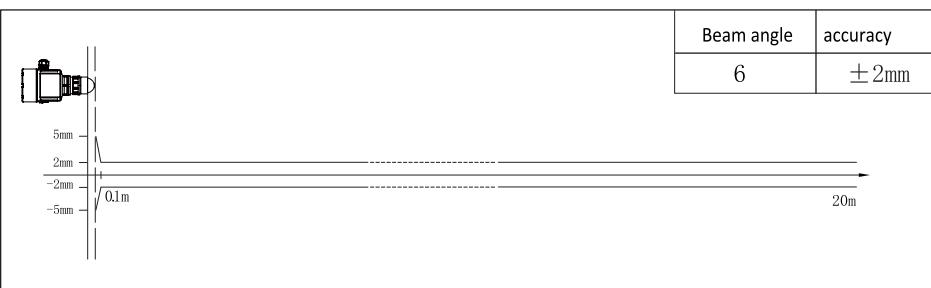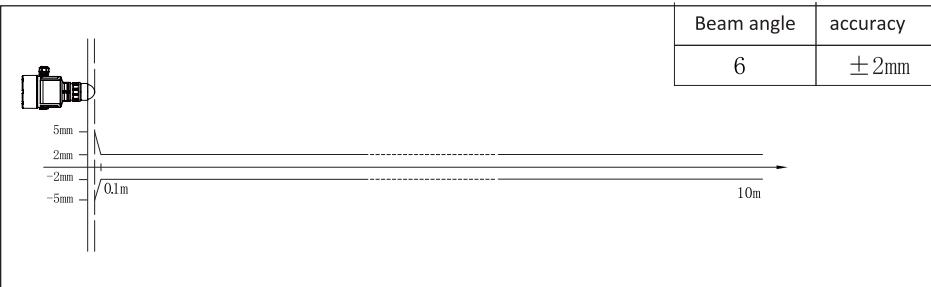
## 9.Transportation and Storage

In addition the transportation and storage conditions of level meter shall also meet the following requirements:

1. The material level meter shall be transported in strict accordance with the characteristics of the product and the requirements of the instructions.

2. The level meter shall be stored in a dry and ventilated room with a temperature of (- 20~60) ℃ and a relative humidity of no more than 80%. Do not mix with corrosive substances. Instruments that have been stored for a long time shall be sold and used after corresponding tests.

Address: 7191 Yonge street, Toronto, Canada

Tel: +16472221281(5 line)

Web: www.madecotech.com

Email: Info@madecotech.com